

# CONSTRUCTION OF THE LAGRANGE MECHANICS OF THE HEREDITARY SYSTEMS

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In current literature term “hereditary” and “rheological” systems are equivalent. In opinion of Работнов Ю.Н. [1], the name “hereditary” system or continuum proposed by В.Вольтерра, is more precise as well as suitable. By use this name, the property of rheological systems “to remember” history of loading is fully described. By series of the fundamental papers and monographs, Mechanics of hereditary continuum is presented. Also, in numerous references, many examples with applications in engineering, biological and other area [2] are published. Mechanics of discrete hereditary systems up to a few years before was presented only by separate single papers [3] and containing only solutions of the partial problems.

Research results in area of mechanics of the hereditary discrete systems, obtained by authors of this paper, are generalized and presented in the monograph [4] which contains first presentation of the analytical dynamics of the hereditary discrete systems. We can conclude that this monograph contains complete foundation of the analytical dynamics theory of discrete hereditary systems and by using these results, numerous examples are obtained and solved (see Refs. [5-12]).

Hereditary system is every system which contains mutual hereditary interaction between material particles in the form of one or more constraints with hereditary properties.

There are three mathematical forms for description of the constitutive relations of the hereditary properties of the hereditary interaction [2], in the building of the hereditary system’s mechanics. These forms are:

1. Differential equation, expressed in the form of dependence reaction force  $P$  of the rheological coordinate  $x$ , usually presented as deformation or relative displacement of the hereditary constraint:

$$\sum_{r=1}^n a_k \frac{d^k P}{dt^k} + P(t) = b_0 x + \sum_{k=1}^n b_k \frac{d^k x}{dt^k} \quad (1)$$

2. Integral equation, expressed in the form of dependence reaction force  $P$  of the rheological coordinate  $x$ , usually presented as deformation or relative displacement of the hereditary constraint:

$$P(t) = c \left( x(t) - \int_0^t R(t-\tau)x(\tau)d\tau \right) \quad (2)$$

By this integral equation, the relaxation of the reaction force  $P$  depending of the rheological coordinate  $x$ , is presented and expressed..

3. Integral equation, expressed in the form of dependence rheological coordinate  $x$ , usually presented deformation or relative displacement of the hereditary constraint and reaction force  $P$ :

$$x(t) = \frac{1}{c} \left[ P(t) + \int_0^t K(t-\tau)P(\tau)d\tau \right], \quad (3)$$

By this integral equation, the retardation of the rheological coordinate  $x$  of the reaction force  $P$  is presented and expressed.

In the previous integral equations  $R(t-\tau)$  and  $K(t-\tau)$  - are relaxational and rheological kernel. .

Previous integral equations (2) and (3), can be expressed in following form:

$$P(t) = c \left( x(t) - \int_0^t R(\tau) x(t-\tau) d\tau \right), \quad (4)$$

$$x(t) = \frac{1}{c} \left( P(t) + \int_0^\infty K(\tau) P(t-\tau) d\tau \right), \quad (5)$$

where by integral operators, the histories of the previously interactions of the hereditary constraints are expressed.

In the basis of the construction of the Lagrange's mechanics of the hereditary discrete systems, the classical mechanics principle are used. These principles are: Principle of the work of the forces along corresponding possible system displacements, as well as Principle of dynamical equilibrium.

Using the Principle of the work of the system forces along corresponding possible system displacements we can write the following equation:

$$\sum_{i=1}^{3N} (m_i \ddot{x}_i - X_i + \sum_{k=1}^K P_k e_{ik}) \delta x_i = 0, \quad (6)$$

where force of rheological reaction  $P_k$  of the rheological interactions between material particles are present because constraint is no ideal.

Lagrange's equations second kind for hereditary systems are in the form:

$$\frac{d}{dt} \frac{\partial T}{\partial \dot{q}_j} - \frac{\partial T}{\partial q_j} = \frac{\partial \Pi}{\partial q_j} + Q_j + \sum_{k=1}^K b_{kj} P_k, \quad j = 1, 2, \dots, n \quad (7)$$

From previous equations, It is necessary to eliminate reaction forces  $P_k$  by use corresponding numbers of the integral equations expressed in the form of dependence reaction force  $P_k$  of the corresponding rheological coordinates in the form (2) or (4) and with corresponding change of the coordinate from Descartes to generalized. Equations (7) are universal because their applications are possible in the case of the arbitrary number of the hereditary interactions between material particles in the system, and also in the sense when number of the hereditary interactions is larger then number of the system degree of freedom,  $K > n$ .

Applications of the Lagrange's equations second kind for hereditary systems in the form (7) with use of the rheological constitutive equations of the rheological interactions in the form (1) or (2) is possible for the case "dynamical defined systems" for which determinant satisfy the following condition  $|b_{kj}(q)| \neq 0$ ,  $K \leq n$ . For these cases Lagrange's equations second kind is easy to solve with respect to the reactions  $P_k$  by use equations (1) or (3).

For description of properties of the dynamics of the hereditary system by use relaxational or rheological kernel (resolvent), these kernels are expressed by exponential or fractional-exponential forms [1]. Description of the hereditary properties of the system by use differential forms (1) and integral form (2) and (3) with exponential kernels is equivalent. For the case of the fractional-exponential forms of the kernel (2) and (3) in the integral form corresponding equivalent differential forms not exist.

Equivalency of the hereditary interactions and reactive forces in the systems of the automatic control gives possibility to extend theory of the analytical dynamics of the hereditary systems to the mechanical systems with automatic control. For example, automat with transfer function presented in the following form

$$W(p) = \frac{b_0 + b_1 p + \dots + b_n p^n}{1 + a_1 p + \dots + a_n p^n} \quad (8)$$

present a hereditary interaction (1) between material particles of the mechanical system.

The Lagrange's mechanics of the hereditary systems is extended and generalized to the thermo-rheological [8] and piezo-rheological [9] mechanical systems.

Methods for solving problems of dynamics of the hereditary systems are considered with special Euler's Gama functions.

Approximation of the expressions for the coefficients of the damping and corresponding decrements as well as for frequency of the oscillations hereditary oscillatory systems are obtained with high accuracy.

**Keywords:** Hereditary system, rheological element, rheological and relaxational kernels, standard hereditary element, integro-differential equation, material particles, rheonomic coordinate, rheological pendulum, rheonomic coordinate, covariant coordinate, thermo-rheological and piezo-rheological hereditary elements.

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